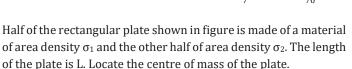
C.O.M OF CONTINUOUS BODIES

Ex. Seven bricks, each of length L, are arranged as shown in the figure. Each brick is displaced with respect to the one in contact by $\frac{L}{10}$ Find the x-coordinate of the centre of mass relative to the origin shown.

Sol. Given, Length of each brick = L Since each brick is symmetrical, the centre of mass of each brick will lie on the corresponding geometric centers, i.e., $\frac{L}{2}$ distance from the end of the brick.

Thus, the centre of masses of the bricks lies as shown in the figure. Now, the x-coordinate of the centre of mass of this system is given as follows:

$$\begin{split} X_{com} &= \frac{\sum_{i=1}^{n} m_i X_i}{\sum_{i=1}^{n} m_i} \\ X_{com} &= \frac{(m+m) \times \frac{L}{2} + (m+m) \times (\frac{L}{2} + \frac{L}{10}) + (m+m) \times (\frac{L}{2} + \frac{2L}{10}) + m \times (\frac{L}{2} + \frac{3L}{10})}{7m} \\ X_{com} &= \frac{L + L + L + \frac{L}{2} + \frac{L}{5} + \frac{2L}{5} + \frac{3L}{10}}{7} = \frac{44L}{70} \end{split}$$





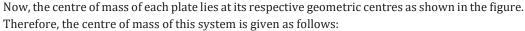
Sol. Given

Ex.

Length of the whole plate = L So, the length of each part is $\frac{L}{2}$

Let m_1 and m_2 be the mass of each plate and A_1 and A_2 be the areas.

$$\begin{aligned} m_1 &= \sigma_1 A_1 = \sigma_1 \times \frac{L^2}{4} \\ m_2 &= \sigma_2 A_2 = \sigma_2 \times \frac{L^2}{4} \end{aligned}$$



$$\begin{split} X_{com} &= \frac{\sum_{i=1}^{2} m_{i} x_{i}}{\sum_{i=1}^{2} m_{i}} \\ X_{com} &= \frac{m_{1} X_{1} + m_{2} X_{2}}{m_{1} + m_{2}} = \frac{(\sigma_{1} \times \frac{L^{2}}{4}) \times (\frac{L}{4}) + (\sigma_{2} \times \frac{L^{2}}{4}) \times (\frac{3L}{4})}{(\sigma_{1} \times \frac{L^{2}}{4}) + (\sigma_{2} \times \frac{L^{2}}{4})} \\ X_{com} &= (\frac{\sigma_{1} + 3\sigma_{2}}{\sigma_{1} + \sigma_{2}}) \times (\frac{L}{4}) \end{split}$$

Centre of Mass of Continuous Bodies

Let's contemplate a body with a continuous distribution of matter; in such a case, the center of mass of the body is determined as follows:

$$x_{com} = \frac{\int_{X} dm}{\int dm}$$

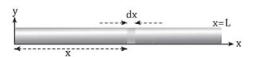
$$y_{com} = \frac{\int y dm}{\int dm}$$

$$z_{com} = \frac{\int z dm}{\int dm}$$



Center of Mass of a uniform rod

Let's examine a rod of mass M and length L positioned along the x-axis, with one end located at the origin. To determine the center of mass of this rod, we'll examine a small element of length dx and mass dm at a distance



X from the origin along the x-axis, as illustrated in the diagram.

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Now, by unitary method, we get,

$$dm = \frac{M}{L} dx$$

The centre of mass is given as follows:

$$\begin{split} X_{com} &= \frac{\int x dm}{\int dm} \\ X_{com} &= \frac{\int_0^L \!\!\! \frac{M}{L} X dx}{M} = \frac{1}{L} \big[\frac{x^2}{2} \big]_0^L \\ X_{com} &= \frac{L}{2} \end{split}$$

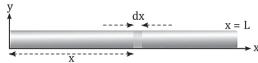
Ex. A rod of length L is placed along the x-axis between x = 0 and x = L. The linear density (λ) of the rod varies with the distance x from the origin as, $\lambda = kx$. Here, k is a positive constant. Find the position of the centre of mass of this rod.



Sol. Given, Linear density of rod, $\lambda = kx$

Length of the rod = L

For finding the centre of mass of this rod, let us consider a small element of length dx and mass dm at a distance x from the origin along the x-axis as shown in the figure.



Now, $dm = \lambda dx = kx dx$

The centre of mass is given as follows:

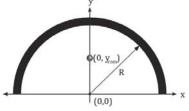
$$\begin{aligned} x_{com} &= \frac{\int x dm}{\int dm} \\ x_{com} &= \frac{\int_{0}^{L} x (kx dx)}{\int_{0}^{L} kx dx} = \frac{k [\frac{x^{3}}{3}]_{0}^{L}}{k [\frac{x^{2}}{2}]_{0}^{L}} \\ x_{com} &= \frac{2L}{2} \end{aligned}$$

Centre of Mass of a Semi-circular Ring

Let's contemplate a uniformly distributed semi-circular ring with radius R and mass M as depicted in the figure.

Because the ring exhibits symmetry about the y-axis, the center of mass will be situated along the y-axis.

Let the coordinates of the centre of mass be $(0, y_{com})$.



Let's examine a tiny element with a length $dl=Rd\theta$ mass dm, which spans an angle $d\theta$ at the center, positioned at an angle θ with respect to the positive x-axis, as illustrated in the figure.

Now, mass of the element is as follows:

$$dm = \frac{M}{\pi R} \times (Rd\theta) = \frac{M}{\pi} d\theta$$

And, $y = R\sin \theta$,

The centre of mass is given as follows:

$$y_{com} = \frac{\int y dm}{\int dm}$$

$$y_{com} = \frac{\int_0^{\pi} (R\sin\theta) (\frac{M}{\pi}) d\theta}{\int_0^{\pi} (\frac{M}{\pi}) d\theta} = \frac{-\frac{MR}{\pi} [\cos\theta]_0^{\pi}}{M}$$

$$y_{com} = \frac{2R}{\pi}$$

Therefore, the coordinates of centre of mass are, $(0, y_{com}) = (0, \frac{2R}{\pi})$.