

MOTION IN A PLANE

RESOLUTION OF VECTORS

Resolution of a Vector in a Plane

All Physical quantities like force, momentum, velocity, acceleration are all vector quantities because they have both magnitude and direction. We represent the vector as an arrow-headed line, where the tip of the arrow is the head and the line is the tail.

Let's suppose there are two paths, viz: A and B, where A and B are horizontal and vertical components of a vector, respectively.

$$\sqrt{3^2} + \sqrt{4^2} = \sqrt{9} + \sqrt{16} = \sqrt{25} = 5$$

So, 5 m is displacement.

Now, let's discuss what is the horizontal and vertical component.

Horizontal Component Definition

In science, we define the horizontal component of a force as the part of the force that moves directly in a line parallel to the horizontal axis.

Let's suppose that you kick a football, so now, the force of the kick can be divided into a horizontal component, which is moving the football parallel to the ground, and a vertical component that moves the football at a right angle to the surface/ground.

Vertical Component Definition

We define the vertical component as that part or a component of a vector that lies perpendicular to a horizontal or level plane.

Resolution of a Vector

Resolution of a vector is the splitting of a single vector into two or more vectors in different directions which together produce a similar effect as is produced by a single vector itself. The vectors formed after splitting are called component vectors.

$OB \rightarrow = a_x$ = vector along the x-axis (It is the horizontal component formula)

$OD \rightarrow = a_y$ = vector along the y-axis (It is the vertical component formula)

From here, we obtained the horizontal and vertical components of a vector, which is a vector a

From the triangle law of addition, we can use the formula as:

$$OC \rightarrow = OB \rightarrow + OD \rightarrow$$

$$a \rightarrow = a_x + a_y \dots (1)$$

Here, we can see that OCB is right-angled, so using the formula of the trigonometric function, we get the angular components along the x and y-axis, respectively:

Since

$$OB/OC = \cos$$

$$OB = OC \cos$$

So,

$$a_x = a \cos$$

Similarly,

$$BC/OC = \sin$$

$$a_y = a \sin \dots$$

Now, eq (3) \div eq (2), we get the tangent of component, which is given by:

$$(a \sin \theta) / (a \cos \theta) = a_y / a_x$$

So,

$$\tan = BC/OB = a_y / a_x \dots (4)$$

Rectangular Components of Vectors in Three Dimensions

We define rectangular components of vectors in Three Dimensions in the following manner:

If the coordinates of a point P, i.e., x, y, and z, the vector joining point P to the origin is called the position vector. The position vector of point P is equal to the sum of these coordinates, which is given by:

$$x + y + z$$

Rectangular Components

Rectangular components of a vector in three dimensions can be better understood by going through the following context:

Let's suppose that vector \vec{A} is presented by the vector \vec{OR}

Now, taking O as the origin and construct a rectangular parallelopiped with its three edges along with the three rectangular axes, viz: X, Y, and Z. Here, we can notice that \vec{A} represents the diagonal of the rectangular parallelopiped whose intercepts are the a_x , a_y , and a_z , respectively. We call these intercepts the three rectangular components of \vec{A}

Now, using the triangular law of vector addition, we have:

$$\vec{OR} = \vec{OS} + \vec{ST} + \vec{TR}$$

Using the parallel law of vector addition, we have:

$$\vec{ST} = \vec{OS} + \vec{OP}$$

$$\vec{OR} = (\vec{OS} + \vec{OP}) + \vec{TR}$$

Here, one must notice that $\vec{TR} = \vec{OQ}$. So, rewriting equation (5) in the following manner:

$$\vec{OR} = (\vec{OS} + \vec{OP}) + \vec{OQ}$$

Or,

$$\vec{A} = \vec{A}_z + \vec{A}_x + \vec{A}_y = \vec{A}_x + \vec{A}_y + \vec{A}_z$$

Therefore,

$$\vec{A} = A_i \vec{x} + A_j \vec{y} + A_k \vec{z}$$

Also,

$$OR^2 = OT^2 + TR^2$$

$$OP^2 + OS^2 + TR^2$$

Now,

$$A^2 = A^2_x + A^2_y + A^2_z$$

Resolution of Rectangular Vectors in Three Dimensions in their Direction Cosines

Now, we can restate equation (6) in the following manner:

$$A = \sqrt{A^2_x + A^2_y + A^2_z}$$

If α , β , and γ are the angles which the vector A makes with the X, Y, and Z-axis, respectively, then we have:

$$\begin{aligned} \cos \alpha &= A_x / A \Rightarrow A_x = A \cos \alpha \\ \cos \beta &= A_y / A \Rightarrow A_y = A \cos \beta \\ \cos \gamma &= A_z / A \Rightarrow A_z = A \cos \gamma \end{aligned}$$

We must note that $\cos \alpha$, $\cos \beta$, and $\cos \gamma$ are direction cosines of vectors A_x , A_y , and A_z ,

Now, putting the values of equations (a), (b), and © in the equation (7), we get

$$A^2 = A^2 \cos^2 \alpha + A^2 \cos^2 \beta + A^2 \cos^2 \gamma \quad \dots (8)$$

So, we get the equation as:

$$\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$$

Here, we conclude that the squares of the direction cosines of three vectors are always constant, i.e., unity.