

**Solution Paper – II**  
**Mathematical Methods in Engineering & Science**

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**Exercise 1**

*Determine if the following system is consistent or not*

$$\begin{cases} 3x_1 + 4x_2 + x_3 = 1 \\ 2x_1 + 3x_2 = 0 \\ 4x_1 + 3x_2 - x_3 = -2. \end{cases}$$

**Solution.**

Step 1: To eliminate the variable  $x_1$  from the second and third equations we perform the operations  $r_2 \leftarrow 3r_2 - 2r_1$  and  $r_3 \leftarrow 3r_3 - 4r_1$  obtaining the system

$$\begin{cases} 3x_1 + 4x_2 + x_3 = 1 \\ x_2 - 2x_3 = -2 \\ -7x_2 - 7x_3 = -10. \end{cases}$$

Step 2: Now, to eliminate the variable  $x_3$  from the third equation we apply the operation  $r_3 \leftarrow r_3 + 7r_2$  to obtain

$$\begin{cases} 3x_1 + 4x_2 + x_3 = 1 \\ x_2 - 2x_3 = -2 \\ -21x_3 = -24. \end{cases}$$

Solving the system by the method of backward substitution we find the unique solution  $x_1 = -\frac{3}{7}, x_2 = \frac{2}{7}, x_3 = \frac{8}{7}$ . Hence the system is consistent ■

**Exercise 2**

*Show that  $(5 + 4s - 7t, s, t)$ , where  $s, t \in \mathbb{R}$ , is a solution to the equation*

$$x_1 - 4x_2 + 7x_3 = 5.$$

**Solution**

$x_1 = 5 + 4s - 7t, x_2 = s$ , and  $x_3 = t$  is a solution to the given equation because

$$x_1 - 4x_2 + 7x_3 = (5 + 4s - 7t) - 4s + 7t = 5. \blacksquare$$

A linear equation can have infinitely many solutions, exactly one solution or no solutions at all.

**Exercise — 3** Find the complex Fourier series of the function

$$f(t) = \begin{cases} 0 & -\pi < t < 0, \\ 1 & 0 < t < \pi. \end{cases}$$

**Solution —** Since the period is  $2\pi$ , so  $p = \pi$ , and the complex Fourier series is given by

$$f(t) = \sum_{n=-\infty}^{\infty} c_n e^{int}$$

with

$$c_0 = \frac{1}{2\pi} \int_0^{\pi} dt = \frac{1}{2},$$

$$c_n = \frac{1}{2\pi} \int_0^{\pi} e^{-int} dt = \frac{1 - e^{-in\pi}}{2\pi ni} = \begin{cases} 0 & n = \text{even}, \\ \frac{1}{\pi ni} & n = \text{odd}. \end{cases}$$

Therefore the complex series is

$$f(t) = \frac{1}{2} + \frac{1}{i\pi} \left( \cdots - \frac{1}{3} e^{-i3t} - e^{-it} + e^{it} + \frac{1}{3} e^{i3t} + \cdots \right).$$

It is clear that

$$c_{-n} = \frac{1}{\pi(-n)i} = \frac{1}{\pi n(-i)} = c_n^*$$

as we expect, since  $f(t)$  is real. Furthermore, since

$$e^{int} - e^{-int} = 2i \sin nt,$$

the Fourier series can be written as

$$f(t) = \frac{1}{2} + \frac{2}{\pi} \left( \sin t + \frac{1}{3} \sin 3t + \frac{1}{5} \sin 5t + \cdots \right).$$

This is also what we expected, since  $f(t) - \frac{1}{2}$  is an odd function, and

$$a_n = c_n + c_{-n} = \frac{1}{\pi ni} + \frac{1}{\pi(-n)i} = 0,$$

$$b_n = i(c_n - c_{-n}) = i \left( \frac{1}{\pi ni} - \frac{1}{\pi(-n)i} \right) = \frac{2}{\pi n}.$$

**Exercise 4**

Use Gauss-Jordan elimination to transform the following matrix first into row-echelon form and then into reduced row-echelon form

$$\begin{pmatrix} 0 & 3 & -6 & 6 & 4 & -5 \\ 3 & -7 & 8 & -5 & 8 & 9 \\ 3 & -9 & 12 & -9 & 6 & 15 \end{pmatrix}$$

**Solution.**

By following the steps in the Gauss-Jordan algorithm we find

Step 1:  $r_3 \leftarrow \frac{1}{3}r_3$

$$\begin{pmatrix} 0 & 3 & -6 & 6 & 4 & -5 \\ 3 & -7 & 8 & -5 & 8 & 9 \\ 1 & -3 & 4 & -3 & 2 & 5 \end{pmatrix}$$

Step 2:  $r_1 \leftrightarrow r_3$

$$\begin{pmatrix} 1 & -3 & 4 & -3 & 2 & 5 \\ 3 & -7 & 8 & -5 & 8 & 9 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{pmatrix}$$

Step 3:  $r_2 \leftarrow r_2 - 3r_1$

$$\begin{pmatrix} 1 & -3 & 4 & -3 & 2 & 5 \\ 0 & 2 & -4 & 4 & 2 & -6 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{pmatrix}$$

Step 4:  $r_2 \leftarrow \frac{1}{2}r_2$

$$\begin{pmatrix} 1 & -3 & 4 & -3 & 2 & 5 \\ 0 & 1 & -2 & 2 & 1 & -3 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{pmatrix}$$

Step 5:  $r_3 \leftarrow r_3 - 3r_2$

$$\begin{pmatrix} 1 & -3 & 4 & -3 & 2 & 5 \\ 0 & 1 & -2 & 2 & 1 & -3 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{pmatrix}$$

Step 6:  $r_1 \leftarrow r_1 + 3r_2$

$$\begin{pmatrix} 1 & 0 & -2 & 3 & 5 & -4 \\ 0 & 1 & -2 & 2 & 1 & -3 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{pmatrix}$$

Step 7:  $r_1 \leftarrow r_1 - 5r_3$  and  $r_2 \leftarrow r_2 - r_3$

$$\begin{pmatrix} 1 & 0 & -2 & 3 & 0 & -24 \\ 0 & 1 & -2 & 2 & 0 & -7 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{pmatrix} \blacksquare$$

It can be shown that no matter how the elementary row operations are varied, one will always arrive at the same reduced row-echelon form; that is the reduced row echelon form is unique (See Theorem 68). On the contrary row-echelon form is **not** unique. However, the number of leading 1's of two different row-echelon forms is the same (this will be proved in Chapter 4). That is, two row-echelon matrices have the same number of nonzero rows. This number is called the **rank** of  $A$  and is denoted by  $\text{rank}(A)$ . In Chapter 6, we will prove that if  $A$  is an  $m \times n$  matrix then  $\text{rank}(A) \leq n$  and  $\text{rank}(A) \leq m$ .

**Exercise - 5** Find the Fourier series for  $f(t)$  which is defined as

$$f(t) = t \quad \text{for } -L < t \leq L, \quad \text{and} \quad f(t + 2L) = f(t).$$

**Solution**

$$f(t) = \frac{1}{2}a_0 + \sum_{n=1}^{\infty} \left( a_n \cos \frac{n\pi t}{L} + b_n \sin \frac{n\pi t}{L} \right),$$

$$a_0 = \frac{1}{L} \int_{-L}^L t \, dt = 0,$$

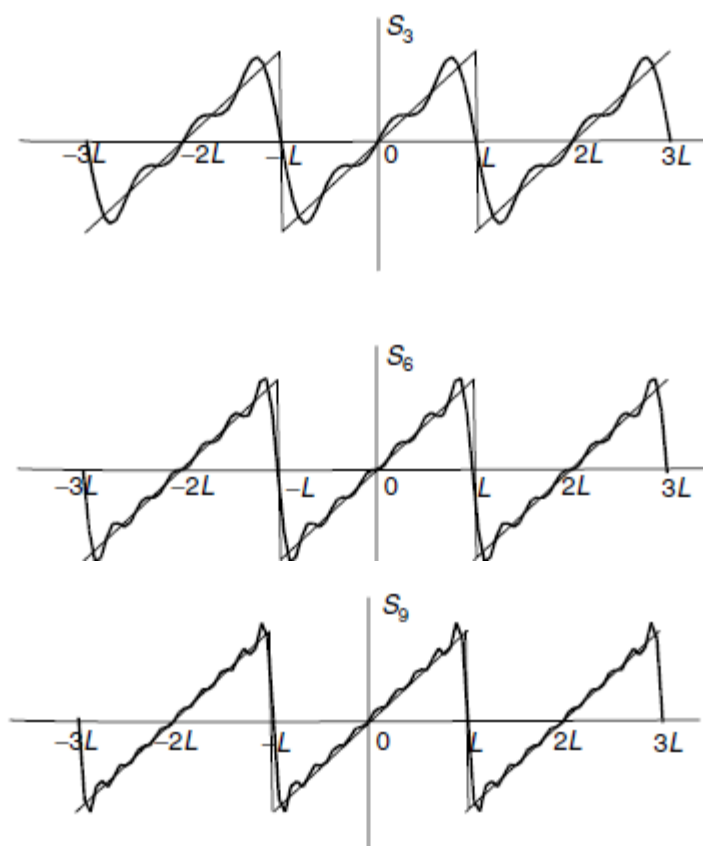
$$a_n = \frac{1}{L} \int_{-L}^L t \cos \frac{n\pi t}{L} dt = \frac{1}{L} \left[ \frac{L}{n\pi} t \sin \frac{n\pi t}{L} + \left( \frac{L}{n\pi} \right)^2 \cos \frac{n\pi t}{L} \right]_{-L}^L = 0,$$

$$\begin{aligned}
b_n &= \frac{1}{L} \int_{-L}^L t \sin \frac{n\pi t}{L} dt \\
&= \frac{1}{L} \left[ -\frac{L}{n\pi} t \cos \frac{n\pi t}{L} + \left( \frac{L}{n\pi} \right)^2 \sin \frac{n\pi t}{L} \right]_{-L}^L = -\frac{2L}{n\pi} \cos n\pi.
\end{aligned}$$

Thus

$$\begin{aligned}
f(t) &= \frac{2L}{\pi} \sum_{n=1}^{\infty} -\frac{1}{n} \cos n\pi \sin \frac{n\pi t}{L} = \frac{2L}{\pi} \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n} \sin \frac{n\pi t}{L} \\
&= \frac{2L}{\pi} \left( \sin \frac{\pi t}{L} - \frac{1}{2} \sin \frac{2\pi t}{L} + \frac{1}{3} \sin \frac{3\pi t}{L} - \dots \right). \quad (1.19)
\end{aligned}$$

The convergence of this series is shown in Fig. 1.3, where  $S_N$  is the partial sum defined as



**Fig. 1.3.** The convergence of the Fourier series for the periodic function whose definition in one period is  $f(t) = t$ ,  $-L < t < L$ . The first  $N$  terms approximations are shown as  $S_N$

$$S_N = \frac{2L}{\pi} \sum_{n=1}^N \frac{(-1)^{n+1}}{n} \sin \frac{n\pi t}{L}.$$

Note the increasing accuracy with which the terms approximate the function. With three terms,  $S_3$  already looks like the function. Except for the Gibbs' phenomenon, a very good approximation is obtained with  $S_9$ .

**Exercise - 6** Find the Fourier series of the function whose definition in one period is

$$f(t) = t^3, \quad -L < t < L.$$

**Solution —** Integrating the Fourier series for  $t^2$  in the required range term-by-term

$$\int t^2 dt = \int \left[ \frac{L^2}{3} + \frac{4L^2}{\pi^2} \sum_{n=1}^{\infty} \frac{(-1)^n}{n^2} \cos \frac{n\pi}{L} t \right] dt,$$

we obtain

$$\frac{1}{3}t^3 = \frac{L^2}{3}t + \frac{4L^2}{\pi^2} \sum_{n=1}^{\infty} \frac{(-1)^n}{n^2} \frac{L}{n\pi} \sin \frac{n\pi}{L} t + C.$$

We can find the integration constant  $C$  by looking at the values of both sides of this equation at  $t = 0$ . Clearly  $C = 0$ . Furthermore, since in the range of  $-L < t < L$ ,

$$t = \frac{2L}{\pi} \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n} \sin \frac{n\pi}{L} t,$$

therefore the Fourier series of  $t^3$  in the required range is

$$t^3 = \frac{2L^3}{\pi} \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n} \sin \frac{n\pi}{L} t + \frac{12L^3}{\pi^3} \sum_{n=1}^{\infty} \frac{(-1)^n}{n^3} \sin \frac{n\pi}{L} t.$$

**Exercise - 7** Find the domain of  $f(x, y) = x \ln(y^2 - x)$ .

Solution. The expression  $x \ln(y^2 - x)$  is defined only when  $y^2 - x > 0$ . That is  $y^2 > x$ . The curve  $y^2 = x$  separates the plane into two regions, one satisfying the inequality  $y^2 > x$ , the other satisfying  $y^2 < x$ . To find out which region is determined by the inequality  $y^2 > x$ . Pick any point in one of the regions and test whether it satisfies the inequality. If it does, then by 'connectivity', that whole region is the one satisfying  $y^2 > x$ , otherwise, it must be the other region. For example, pick the point  $(3, 2)$ . Since  $2^2 > 3$ , the region satisfying  $y^2 > x$  is the one containing  $(3, 2)$ . Thus, domain of  $f$  is  $\{(x, y) \in \mathbb{R}^2 \mid y^2 > x\}$ .

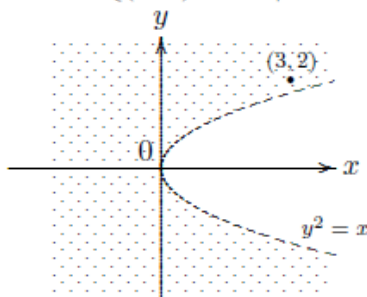


Figure 39 Domain of  $x \ln(y^2 - x)$

**Exercise - 8** Find the distance between the skew lines:

$$L_1 : x = 1 + t, y = -2 + 3t, z = 4 - t$$

$$L_2 : x = 2s, y = 3 + s, z = -3 + 4s$$

Solution. As  $L_1$  and  $L_2$  are skew, they are contained in two parallel planes respectively. A normal to these two parallel planes is given by

$$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 3 & -1 \\ 2 & 1 & 4 \end{vmatrix} = \langle 13, -6, -5 \rangle.$$

Let  $s = 0$  in  $L_2$ . We get the point  $(0, 3, -3)$  on  $L_2$ . Therefore, an equation of the plane containing  $L_2$  is  $\langle x - 0, y - 3, z - (-3) \rangle \cdot \langle 13, -6, -5 \rangle = 0$ . That is  $13x - 6y - 5z + 3 = 0$ . Let  $t = 0$  in  $L_1$ . We get the point  $(1, -2, 4)$  on  $L_1$ . Thus, the distance between  $L_1$  and  $L_2$  is given by

$$\frac{|13(1) - 6(-2) - 5(4) + 3|}{\sqrt{13^2 + (-6)^2 + (-5)^2}} = \frac{8}{\sqrt{230}}.$$

**Exercise - 9** Find the Laplace transform of

$$f(t) = \begin{cases} 1, & 0 \leq t < 2, \\ t - 2, & 2 \leq t. \end{cases}$$

**Solution.**

We do this by definition:

$$\begin{aligned}F(s) &= \int_0^{\infty} e^{-st} f(t) dt = \int_0^2 e^{-st} dt + \int_2^{\infty} (t-2)e^{-st} dt \\&= \left. \frac{1}{-s} e^{-st} \right|_{t=0}^2 + (t-2) \left. \frac{1}{-s} e^{-st} \right|_{t=2}^{\infty} - \int_2^{\infty} \frac{1}{-s} e^{-st} dt \\&= \frac{1}{-s} (e^{-2s} - 1) + (0 - 0) + \frac{1}{s} \left. \frac{1}{-s} e^{-st} \right|_{t=2}^{\infty} = \frac{1}{-s} (e^{-2s} - 1) + \frac{1}{s^2} e^{-2s}\end{aligned}$$

**Exercise - 10** Find the eigenvalues of  $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$  and find all eigenvectors.

**Solution.** The characteristic equation of  $A$  is  $\lambda^2 - 4\lambda + 3 = 0$ , or

$$(\lambda - 1)(\lambda - 3) = 0.$$

Hence  $\lambda = 1$  or  $3$ . The eigenvector equation  $(A - \lambda I_n)X = 0$  reduces to

$$\begin{bmatrix} 2 - \lambda & 1 \\ 1 & 2 - \lambda \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix},$$

or

$$\begin{aligned}(2 - \lambda)x + y &= 0 \\ x + (2 - \lambda)y &= 0.\end{aligned}$$

Taking  $\lambda = 1$  gives

$$\begin{aligned}x + y &= 0 \\ x + y &= 0,\end{aligned}$$



which has solution  $x = -y$ ,  $y$  arbitrary. Consequently the eigenvectors corresponding to  $\lambda = 1$  are the vectors  $\begin{bmatrix} -y \\ y \end{bmatrix}$ , with  $y \neq 0$ .

Taking  $\lambda = 3$  gives

$$\begin{aligned} -x + y &= 0 \\ x - y &= 0, \end{aligned}$$

which has solution  $x = y$ ,  $y$  arbitrary. Consequently the eigenvectors corresponding to  $\lambda = 3$  are the vectors  $\begin{bmatrix} y \\ y \end{bmatrix}$ , with  $y \neq 0$ .