

Introduction to Friction

Friction is the **force** resisting the relative motion of solid surfaces, fluid layers, and material elements sliding against each other. There are several types of friction:

- **Dry friction** resists relative lateral motion of two solid **surfaces** in contact. Dry friction is subdivided into *static friction* ("**stiction**") between non-moving surfaces, and *kinetic friction* between moving surfaces.
- **Fluid friction** describes the friction between layers within a **viscous** fluid that are moving relative to each other.
- **Lubricated friction** is a case of fluid friction where a fluid separates two solid surfaces.
- **Skin friction** is a component of **drag**, the force resisting the motion of a solid body through a fluid.
- **Internal friction** is the force resisting motion between the elements making up a solid material while it undergoes **deformation**.¹

When surfaces in contact move relative to each other, the friction between the two surfaces converts **kinetic energy** into **heat**. This property can have dramatic consequences, as illustrated by the use of friction created by rubbing pieces of wood together to start a fire. Kinetic energy is converted to heat whenever motion with friction occurs, for example when a **viscous** fluid is stirred. Another important consequence of many types of friction can be **wear**, which may lead to performance degradation and/or damage to components. Friction is a component of the science of **tribology**.

Static friction

Static friction is friction between two or more solid objects that are not moving relative to each other. For example, static friction can prevent an

object from sliding down a sloped surface. The coefficient of static friction, typically denoted as μ_s , is usually higher than the coefficient of kinetic friction.

The static friction force must be overcome by an applied force before an object can move. The maximum possible friction force between two surfaces before sliding begins is the product of the coefficient of static friction and the normal force: $f = \mu_s F_n$. When there is no sliding occurring, the friction force can have any value from zero up to F_{max} . Any force smaller than F_{max} attempting to slide one surface over the other is opposed by a frictional force of equal magnitude and opposite direction. Any force larger than F_{max} overcomes the force of static friction and causes sliding to occur. The instant sliding occurs, static friction is no longer applicable—the friction between the two surfaces is then called kinetic friction.

An example of static friction is the force that prevents a car wheel from slipping as it rolls on the ground. Even though the wheel is in motion, the patch of the tire in contact with the ground is stationary relative to the ground, so it is static rather than kinetic friction.

The maximum value of static friction, when motion is impending, is sometimes referred to as **limiting friction**, although this term is not used universally. It is also known as traction.

Kinetic friction

Kinetic (or dynamic) friction occurs when two objects are moving relative to each other and rub together (like a sled on the ground). The coefficient of kinetic friction is typically denoted as μ_k , and is usually less than the coefficient of static friction for the same materials. However, [Richard Feynman](#) comments that "with dry metals it is very hard to show any difference."

New models are beginning to show how kinetic friction can be greater than static friction. Kinetic friction is now understood, in many cases, to be primarily caused by chemical bonding between the surfaces, rather than interlocking asperities; however, in many other cases roughness effects are dominant, for example in rubber to road friction. Surface roughness and

contact area, however, do affect kinetic friction for micro- and nano-scale objects where surface area forces dominate inertial forces.

Angle of friction

For the maximum angle of static friction between granular materials, see [Angle of repose](#).

For certain applications it is more useful to define static friction in terms of the maximum angle before which one of the items will begin sliding. This is called the *angle of friction* or *friction angle*. It is defined as:

$$\tan \theta = \mu_s$$

where θ is the angle from vertical and μ_s is the static coefficient of friction between the objects. This formula can also be used to calculate μ_s from empirical measurements of the friction angle.

Energy of friction

According to the law of conservation of energy, no energy is destroyed due to friction, though it may be lost to the system of concern. Energy is transformed from other forms into heat. A sliding hockey puck comes to rest because friction converts its kinetic energy into heat. Since heat quickly dissipates, many early philosophers, including Aristotle, wrongly concluded that moving objects lose energy without a driving force.

When an object is pushed along a surface, the energy converted to heat is given by:

$$E_{th} = \mu_k \int F_n(x) dx$$

where

F_n is the normal force,

μ_k is the coefficient of kinetic friction,

x is the coordinate along which the object transverses.

Energy lost to a system as a result of friction is a classic example of thermodynamic irreversibility.

Work of friction

In the reference frame of the interface between two surfaces, static friction does *no* work, because there is never displacement between the surfaces. In the same reference frame, kinetic friction is always in the direction opposite the motion, and does *negative* work. However, friction can do *positive* work in certain frames of reference. One can see this by placing a heavy box on a rug, then pulling on the rug quickly. In this case, the box slides backwards relative to the rug, but moves forward relative to the frame of reference in which the floor is stationary. Thus, the kinetic friction between the box and rug accelerates the box in the same direction that the box moves, doing *positive* work.

The work done by friction can translate into deformation, wear, and heat that can affect the contact surface properties (even the coefficient of friction between the surfaces). This can be beneficial as in polishing. The work of friction is used to mix and join materials such as in the process of friction welding. Excessive erosion or wear of mating surfaces occur when work due frictional forces rise to unacceptable levels. Harder corrosion particles caught between mating surfaces (fretting) exacerbates wear of frictional forces. Bearing seizure or failure may result from excessive wear due to work of friction. As surfaces are worn by work due to friction, fit and surface finish of an object may degrade until it no longer functions properly.